Subject: Re: arbitrary rotation of 3-d arrays
Posted by Michael Asten on Fri, 11 Jun 1999 07:00:00 GMT
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Not sure how sophisticated you want to be here.

The !P.T structure makes it easy to start in idl. See online documentation under "Three-dimensional graphics" for starters - including the demo routine HOUSE.PRO

The demo shows how to rotate coordinates for the purpose of making a 2D projection, but the same tools work for rotating 3D arrays as abstract entities.

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When I want to rotate a set of coordinates given by vectors Xin, Yin, Zin,
in 3D, I generate a !P.T transformation using the following
; 3D coordinates before rotation are in vectors Xex,Yex,Zex
t3d,/reset
t3d,rotate=[0.,0.,plu] & t3d,rotate=[-dip,0.,0.] & t3d,rotate=[0.,0.,str]
t3d,translate=[xsh,ysh,zsh]
; we have set up t3d to rotate a body thru a strike(-azimuthal) angle str,
   a dip angle dip, and a plunge angle plu,
 and we have added a translation of position of the refernce point of the
body
  to (xsh,ysh,zsh).
 we now execute the rotation and translation
do_rotation,xex,yex,zex,xrot,yrot,zrot
; and can plot or otherwise operate on the new rotated coordinates howsoever
we; please
end; of demo
The routine to do the rotation and translation is simply:
 routine to perform rotation of n points in x[0:n-1],y[ ] and z[ ]
   using the existing !P.T transformation
 input: xin, yin zin being arrays of reals
 output: xout, yout, zout being arrays of reals, for transformed points
 Author: Michael Asten, Monash University, Melbourne Australia. June 1999.
pro do rotation, xin, yin, zin, xout, yout, zout
 P=fltarr(4,n elements(xin))
 P[0,^*]=xin \& P[1,^*]=yin \& P[2,^*]=zin \& P[3,^*]=1.
 P=transpose(P)
 Prot=P#!P.T; do rotation and shift
 Prot=transpose(Prot)
 xout=Prot[0,*]/Prot[3,*]
 yout=Prot[1,*]/Prot[3,*]
 zout=Prot[2,*]/Prot[3,*]
end
```

"D. Mattes" wrote:

- > hello idl users:
- > has anybody out there in idl-land written or seen code to apply arbitrary
- > rotations to 3-d arrays???

>

> thanks in advance!

> david mattes