Subject: Re: Cell boundary program?
Posted by Alexandros Pertsinidi on Tue, 08 Aug 2000 07:00:00 GMT
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I'm a new IDL user and I don't know much about objects. What would I do with a IDLgrROIGroup once I have it? How would I plot an outline? Thanks a lot!!

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Rachel
Richard Adams wrote in message ...
>> The other method, convolution is also quick, but the returned indices are
in
>> scan-line order. In this case, all the boundary pixels are included.
This
>> method was suggested by ... uhoh, I forgotten who it was right now,
sorry.
>> Here's the steps as described on the newsgroup by the unknown author.
>>
>> bb = convol(Image, replicate(1,3,3),9,/center)
>> Edges = Where(bb gt 0 AND bb LT 255)
>> bb[*] = 0
>> bb[edges] = 255; make this new image just edges
>> bb = Image AND BB; now keep just those edges inside your object
>> perimeter = where(bb eq 255); these are indices to final outline
>>
> Actually I am guilty of the second method. I can add to that what I hope is
> an improved version. Pass the autotrace function a greyscale image and a
> threshold level or range and it returns to you a IDLgrROIGroup of all the
> outlines it finds. It can be slow on complex images. You could take out the
> trace outline function to get just one outline, if you know where it
starts.
> There are several possible improvements and maybe bug fixes - I haven't
> gotten to use it much since I wrote it. I could be made into a nice object
> with methods to get each outline by location or size, and it could be given
> an interactive widget to make selection easier. It also only uses
> 4-connectivity and could be better converted to 8-connectivity (you might
> lose some corners on the outlines). I'll may fix it if I get time,
otherwise
> somebody else could :-)
>
> I hope it is useful, Richard.
> function autotrace, image, select_range
>
>;
> ; Given an image (greyscale) and a selection range - either a single grey
> level or a min/max range
```

```
> ; return a IDLgrROIGroup that corresponds to the 4-connected outline of
each
> selected region
>;
>
    outlines = obj_new('IDLgrROIGroup')
>
    image_size = size(image, /dimensions)
>
    work_image = bytarr(image_size[0], image_size[1])
>
    if n elements(select range) eq 1 then selected = where(image eq
> select range, count) $
      else selected = where((image ge min(select_range)) and (image le
>
> max(select range)), count)
    if count eq 0 then return, outlines
>
    work_image[selected] = 255
>
    bb = convol(work_image, replicate(1,3,3),9,/center)
>
    edges = Where(bb gt 0 AND bb LT 255)
>
    bb[*] = 0
>
    bb[edges] = 255; make this new image just edges
>
    work image = work image AND bb; now keep just those edges
>
    edges = where(work image eq 255, count)
>
>
    repeat begin; search for each outline
>
      edges = where(work_image eq 255, count)
>
      if count gt 0 then begin
>
         start = edges[0]
>
         new_roi = trace_outline(work_image, start)
>
         outlines->Add, new_roi
>
         endif
>
      endrep until count eq 0
>
    return, outlines
>
> end
>
> function get_neighbour_index, start, nx, ny, first_dir
>
> ; get indices for maze tracing.
> ; relative to direction of last step, look left, forward, right, back in
> that preferred order
> ; first check that each step is in bounds for our image
> ; make an array of those indices
> ; shift array to get absolute direction into relative directions
> ; see which indices are valid
>; remember which absolute directions these correspond to
>
    right = 0
   down = 1
   left = 2
   up = 3
    above = start lt nx ? -1 : start - nx
```

```
below = start / nx eq ny - 1 ? -1 : start + nx
>
    to right = start mod nx eq nx - 1 ? -1 : start + 1
>
    to_left = start mod nx eq 0 ? -1 : start - 1
>
    neighbours = [below, to_left, above, to_right]
>
    neighbours = shift(neighbours, -first_dir)
>
>
    directions = shift([right, down, left, up], -first_dir + 1)
    valid = neighbours ge 0
>
    return, [[valid], [neighbours], [directions]]; [which are valid, their
> indices, their directions]
> end
>
> function trace outline, image, start
    image_size = size(image, /dimensions)
>
    done = 0
>
    direction = 0; right to start
>
    current = start
>
    verts = [current]
>
    while not done do begin
>
       search = get neighbour index(current, image size[0], image size[1],
>
> direction)
       s_valid = where(search[*, 0] eq 1, s_count)
>
       if s count eq 0 then stop; should not happen unless 1 pixel image!
>
       s_index = reform(search[*, 1])
>
       s_dirs = reform(search[*, 2])
>
       next_edge = where(image[s_index[s_valid]] eq 255, n_count)
>
       if n count ge 1 then begin
>
         current = s_index[s_valid[next_edge[0]]]
>
         verts = [verts, current]
>
         direction = s dirs[s valid[next edge[0]]]
>
         done = current eq start
>
         endif else done = 1
>
       endwhile
>
    image[verts] = 0
>
    x = verts mod image_size[0]
>
    y = verts / image_size[1]
>
    oOutline = obj_new('IDLgrRoi', x, y)
>
    return, oOutline
> end
```