Subject: Re: Gridding options Posted by Ben Tupper on Tue, 29 Aug 2000 07:00:00 GMT View Forum Message <> Reply to Message

Craig Markwardt wrote:

>

- > I don't exactly understand what your data is like. It sounds like you
- > have 0.5 m x 15000 m resolution, ie. extremely well sampled along one
- > axis and poorly sampled along another. If that's the case, then the
- > following description may need to be modified.

You have the right idea. The ship traveled along a long (mostly) straight path. Every 10-20km the vessel stops and drops the CTD overboard, sampling every 0.5 m over a total depth of 50m - 200m.

- > I will describe my situation. I have irregularly sampled data points,
- > which I wish to place on a regularly sampled 2D grid. In my case the
- > resolution in X and Y is equal. The measured data values are noisy,
- so some form of averaging/smoothing is desireable.

>

- > My solution was to essentially convolve the measured points by a
- > spatial response function. In my case it is the intrinsic spatial
- > response function of the measuring instrument, but a gaussian will
- > probably do fine for you. Clearly you would want to tune the
- > parameters of your gaussian to be appropriate for your problem
- > (considering the spacing and noisiness of the data). The trick is to
- > maintain the data and weighting functions separately, and divide them
- > at the end. This provides a very natural weighting of nearby -- and
- > even overlapping -- data points.

>

- > Here is an example. Suppose that your data is sampled at X and Y,
- > with value Z. This example extends to more measurements trivially.
- > You are interested in making a MAP in the range [X0,X1] and [Y0,Y1],
- > in a NXBINS x NYBINS array. The response function is RESP, an NRX x
- > NRY array: this is the gaussian, which should be centered at
- > RESP[NX/2,NY/2]. Here is my solution, with the real work being done
- > in the "drizzle" section. Yes, a loop!

- > ;; Discretize the positional values to IX And IY
- > xbinsize = (x1-x0)/nxbins
- > ybinsize = (y1-y0)/nybins
- > ix = round((x-x0)/xbinsize) nrx
- iy = round((y-y0)/ybinsize) nry

- > ;; Make sure we keep all values in-bounds
- > wh = where(ix GE 0 AND ix LT nxbins-nrx AND iy GE 0 AND iy LT nybins-nry, ct)

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> if ct EQ 0 then $
  message, 'ERROR: no data within grid limits'
> ix = ix(wh) & iy = iy(wh)
> iz = z(wh)
>
> ;; Drizzle the points onto the map
> map = dblarr(nxbins, nybins) & xmap = map & wmap = map
> for i = 0L, ct-1 do begin
    map(ix(i),iy(i)) = map(ix(i):ix(i)+nrx-1,iy(i):iy(i)+nry-1) + resp*iz(i)
   xmap(ix(i),iy(i)) = xmap(ix(i):ix(i)+nrx-1,iy(i):iy(i)+nry-1) + resp
> endfor
> ;; Compute the weighted, convoluted map by dividing the data by the weighting
> wh = where(xmap GT 0)
> wmap(wh) = map(wh) / xmap(wh)
>
> Maybe this helps!
>
> Craig
I do see what you are describing. This is guite similar (in methodology) to the
iterative gridding process used by a built in function GRID in PV-Wave (which I
am not using.)
How are NRX and NRY, for the response function, determined?
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Thanks, Ben

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note: email address new as of 25JULY2000