Subject: Re: Fitting curves

Posted by larkum on Tue, 06 Sep 1994 08:03:30 GMT

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Once again, thank you to all that replied.

Thanks to the people that responded and particularly to Amara Graps for the example procedures that solved my problem very quickly.

I thought I would post a follow-up as some may be in the same position as I was and others may find the experience interesting. My problem was that somehow I hadn't got the message that you were actually supposed to rewrite the built-in FUNCT procedure with the appropriate function. It still seems kind of clumsy to me.

Anyway, during the search for information I down-loaded some archives of comp.lang.idl-pvwave from IDLmeteo (ftp.sma.ch, /pub/idlmeteo/News_Archives) which I will go straight to next time, since it is a source of information better even than the FAQ. I found a discussion in which David Hembroff had made a similar plea for help and had been given a succint and useful reply from Eric Korpela. From his reply it appears to me that there are different versions of CURVEFIT floating around. Specifically, his procedure uses the keyword FUNCTION NAME which is a string that gives the name of the procedure to be used in place of FUNCT. This is a much better idea, but it isn't part of the procedure we got with our version of PV-Wave version 4.2.

On the other hand, I liked the modifications made by Amara Graps in his version of CURVEFIT, so I put in the (trivial) code to include the FUNCTION NAME keyword into CURVEFIT and the resulting MYCURVEFIT is given below.

\$Id: curvefit.pro,v 1.1 1991/03/29 12:27:07 jeffry Exp \$ PRO MYCURVEFIT, X, Y, W, A, SIGMAA, YFIT, COVAR, function_name=function_name :+ : NAME: : MYCURVEFIT : PURPOSE: ; Non-linear least squares fit to a function of an arbitrary number of parameters. Function may be any non-linear function where : the partial derivatives are known or can be approximated. **CATEGORY:** ; E2 - Curve and Surface Fitting : CALLING SEQUENCE:

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; MYCURVEFIT,X,Y,W,A,SIGMAA,YFIT,COVAR
: INPUTS:
X = Row vector of independent variables.
Y = Row \ vector \ of \ dependent \ variable, \ same \ length \ as \ x.
 W = Row vector of weights, same length as x and y.
 For no weighting
 w(i) = 1., instrumental weighting w(i) =
 1./y(i), etc.
 A = Vector of nterms length containing the initial estimate
 for each parameter. If A is double precision, calculations
 are performed in double precision, otherwise in single prec.
INPUT PARAMETERS:
 FUNCTION_NAME = Fitting function to be used. The default
 is the Gaussian function defined in FUNCT.
 OUTPUTS:
 A = Vector of parameters containing fit.
 Function result = YFIT = Vector of calculated
 values.
    Covariance matrix= error of YFIT showing correlations
 Sigmaa = Vector of standard deviations for parameters
 Α.
 COMMON BLOCKS:
 NONE.
 SIDE EFFECTS:
The function to be fit must be defined and called FUNCT.
For an example see FUNCT in the IDL User's Library.
Call to FUNCT is:
; FUNCT,X,A,F,PDER
; Alternatively, the FUNCTION NAME keyword can be used to
specify a different procedure definition
where:
; X = Vector of NPOINT independent variables, input.
; A = Vector of NTERMS function parameters, input.
F = Vector of NPOINT values of function, y(i) = funct(x(i)), output.
 PDER = Array, (NPOINT, NTERMS), of partial derivatives of funct.
 PDER(I,J) = Derivative of function at ith point with
 respect to jth parameter. Optional output parameter.
 PDER should not be calculated if parameter is not
 supplied in call (Unless you want to waste some time).
 RESTRICTIONS:
 NONE.
 PROCEDURE:
 Copied from "CURFIT", least squares fit to a non-linear
function, pages 237-239, Bevington, Data Reduction and Error
 Analysis for the Physical Sciences.
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compines the best features of the gradient search with
the method of linearizing the fitting function."
Iterations are perform until the chi square changes by
only 0.1% or until 20 iterations have been performed.
The initial guess of the parameter values should be
as close to the actual values as possible or the solution
may not converge.
MODIFICATION HISTORY:
Written, DMS, RSI, September, 1982.
Modified ;to output covariance matrix, ALG ,August 1987
Modified; function_name keyword, Matthew Larkum, September, 1994
if not keyword set(function name) then function name = 'FUNCT'
ON ERROR,2 ;RETURN TO CALLER IF ERROR
A = 1.*A; MAKE PARAMS FLOATING
NTERMS = N ELEMENTS(A);# OF PARAMS.
NFREE = (N_ELEMENTS(Y) < N_ELEMENTS(X)) - NTERMS ; Degs of freedom
IF NFREE LE 0 THEN STOP, 'Curvefit - not enough points.'
FLAMBDA = 0.001 ;Initial lambda
DIAG = INDGEN(NTERMS)*(NTERMS+1) :SUBSCRIPTS OF DIAGONAL ELEMENTS
FOR ITER = 1,20 DO BEGIN : Iteration loop
EVALUATE ALPHA AND BETA MATRICIES.
ok = execute(function_name + ',X,A,YFIT,PDER') ;COMPUTE FUNCTION AT A.
BETA = (Y-YFIT)*W # PDER
ALPHA = TRANSPOSE(PDER) # (W # (FLTARR(NTERMS)+1)*PDER)
CHISQ1 = TOTAL(W*(Y-YFIT)^2)/NFREE :PRESENT CHI SQUARED
INVERT MODIFIED CURVATURE MATRIX TO FIND NEW PARAMETERS.
REPEAT BEGIN
C = SQRT(ALPHA(DIAG) # ALPHA(DIAG))
ARRAY = ALPHA/C
ARRAY(DIAG) = (1.+FLAMBDA)
ARRAY = INVERT(ARRAY)
B = A+ ARRAY/C # TRANSPOSE(BETA); NEW PARAMS
ok = execute(function_name+',X,B,YFIT') ;EVALUATE FUNCTION
CHISQR = TOTAL(W*(Y-YFIT)^2)/NFREE ;NEW CHISQR
FLAMBDA = FLAMBDA*10. ;ASSUME FIT GOT WORSE
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; "This method is the Gradient-expansion algorithm which

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FLAMBDA = FLAMBDA/100. ;DECREASE FLAMBDA BY FACTOR OF 10
A=B ;SAVE NEW PARAMETER ESTIMATE.
PRINT,'ITERATION =',ITER,' ,CHISQR =',CHISQR
PRINT,A
IF CHISQ1 eq 0 or ((CHISQ1-CHISQR)/CHISQ1) LE .001 THEN GOTO,DONE ;Finished?
ENDFOR ;ITERATION LOOP
;
PRINT,'CURVEFIT - Failed to converge'
;
DONE: ok = execute(function_name+',X,A,YFIT,PDER')
ALPHA = TRANSPOSE(PDER) # (W # (FLTARR(NTERMS)+1)*PDER)
COVAR = INVERT(ALPHA)
SIGMAA = SQRT(COVAR(DIAG)) ;RETURN SIGMA'S
```

END