
Subject: Re: Averaging quaternions

Posted by [Arnold Neumaier](#) on Sun, 21 Mar 2004 17:48:33 GMT

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jelansberry wrote:

> "Arnold Neumaier" <Arnold.Neumaier@univie.ac.at> wrote in message

> news:405D56B6.6030403@univie.ac.at...

>

>> jelansberry wrote:

>>

>>> I would compute the average of the

>>> Euler angles, and then convert the resulting average Euler angles back to a

>>> quaternion (convert the Euler angles to a direction cosine matrix, then

>>> extract the quaternion).

>>

>> This has exactly the same problems as averaging over quaternions, since

>> angles are only unique up to a multiple of π or 2π ; so the average

>> depends on whether you represent an angle by a number close to π or

>> close to $-\pi$...

>>

>> Arnold Neumaier

>>

>

>

> "Uniqueness" of the Euler angles is not the issue, it's more an issue of

> continuity of the angles. Euler angles do not have the "same" problems as

> averaging over quaternions. My basic beef with averaging quaternions is

> that the initial result of the average is not a quaternion (i.e., the result

> does not have unit norm). Euler angles do not suffer from such a

> complication.

The real part of a unit quaternion (with nonnegative real part)

is redundant in that it can be recomputed from the imaginary part.

Thus averaging the imaginary parts and recomputing the real part

would be a simpler recipe of the same kind as yours with Euler angles.

And it would have exactly the same problems as the average-and-scale

method, although there are no singularities. It is a matter of

non-uniqueness in both cases, which implies that one must make ad hoc

normalizations: A choice of sign in the quaternion case, and a choice

of some normalization interval in the Euler case. This cannot be

done without introducing discontinuities - these are not present

in the mathematics but only in the normalization chosen.

> If all the OP is doing is trying to find the average attitude over some

> fairly small period of time, then one might expect the Euler angles

> corresponding to the quaternion samples to fairly continuous.

Not if one of the angle is just a little less than π and increasing

beyond π (suddenly becoming $-\pi$)

- > I agree (and my post gave fair warning) that with Euler angles one has to be
- > careful of choosing sequences near the singularity of the sequence.

AND near the normalization bounds! The average-and-scale technique is thus even better since it has no singularities and only the problem with possible discontinuities in the representation.

Arnold Neumaier
