
Subject: Re: Averaging quaternions

Posted by [Arnold Neumaier](#) on Sun, 21 Mar 2004 08:47:50 GMT

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jelansberry wrote:

- > I've finally realized that all I contributed was questions and complaints
- > and no alternative solutions.
- >
- > If I were doing this, I would probably convert the quaternions to Euler (or
- > Bryant) angles first (convert the quaternion to a direction cosine matrix,
- > then extract the Euler angles). Then, I would compute the average of the
- > Euler angles, and then convert the resulting average Euler angles back to a
- > quaternion (convert the Euler angles to a direction cosine matrix, then
- > extract the quaternion).

This has exactly the same problems as averaging over quaternions, since angles are only unique up to a multiple of π or 2π ; so the average depends on whether you represent an angle by a number close to π or close to $-\pi$...

Arnold Neumaier
