Subject: Re: coordinates & transforms & plotting Posted by David Fanning on Mon, 28 Feb 2005 14:28:06 GMT

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Ralf Schaa writes:

- > Okay folks,
- >
- > 1.)
- > I have refreshed linear algebra and if I have it right, there is not a
- > unique basis for vectors or points in 3D...so what does IDL take as a
- > basis when plotting in 3D?

I'm not sure what a "basis" is, but a coordinate frame consists of an origin (perhaps what you are calling the basis) and three orthogonal axes. The origin of the IDL coordinate system is the (0,0,0) point in the lower-left corner of the window, with the X axis horizontal, the Y axis vertical, and the Z axis coming out toward you.

- > 2.)
- > And how can I manipulate that in a way it takes *my* basis?

Typically, in IDL you set up the 3D transformation matrix with calls to T3D. You set a new "origin" with the TRANSLATE keyword.

Cheers,

David

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Covote's Guide to IDL Programming: http://www.dfanning.com/