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Subject: Re: New Image Processing Routines  
Posted by [Marshall Perrin](#) on Fri, 21 Apr 2006 17:24:01 GMT  
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David Fanning <davidf@dfanning.com> wrote:

- > I've since moved on to more pressing things, but maybe
- > I'll have to revisit this. Let me know if a few hours of
- > sleep leads you to some more ideas. :-)

Actually, it was while brushing my teeth that I had the epiphany.  
The relevant line of code is the scaling, of course:

```
output = Scale_Vector(ASinhScl_ASinh(alpha*beta*Temporary(output))/beta, $  
    minOut, maxOut, /NAN, Double=1)
```

The only way in which alpha affects things is as a multiplicative constant times the input (also named 'output' above just to be tricky :-). We know that it's the ratio of beta to the input that sets the amount of nonlinearity in the data. Quoting from Lupton et al 1999, right after eq. 4:

For  $x \rightarrow \infty$ ,  $\mu$  approaches  $m$  for any choice of  $\beta$ . On the other hand, when  $|x| \ll b$ ,  $\mu$  is linear in  $x$ .

So it's the ratio of beta to  $x$  that matters, and since alpha just has the effect of scaling  $x$ , it doesn't actually add an additional degree of freedom. I'm fully convinced now that alpha doesn't give you anything new.

Next problem: the beta in your code (and in all the other IDL implementations of asinh scaling, as far as I can tell!) is actually the \*inverse\* of the parameter  $b$  in Lupton et al. Quoting now from Lupton et al. 2004, shortly after Eq. 2:

We take  $F = \text{arcsinh}(x/\text{Beta})$ , where the softening parameter Beta is chosen to bring out the desired details.

So they say they are dividing the input by Beta, while you're multiplying it. Actually, they \*say\* they are dividing the input by Beta, but if you download their code from <http://cosmo.nyu.edu/hogg/visualization/> and look at `nw_asinh_fit.pro`, the relevant line of code is

```
val = asinh(radius*nonlinearity)/nonlinearity
```

The same approach is used in Dave Schlegel's `djs_rgb_make` available in his IDLUTILS library. So it seems that they've defined `nonlinearity = 1./beta`. Right? And thus your Beta is the inverse of theirs.

Does this actually matter? No, not really. Either way works fine. It's

just a slightly confusing state of affairs for anyone trying to match up IDL code to published algorithms. I *think* the simplest solution is to rename in your code "beta" to "nonlinearity" and put in a note that  $\text{nonlinearity} = 1./b$ . But hey, who am I to tell you what to name your variables? :-)

Another thing possibly worth adding to the documentation is that if you have some estimate of the noise in your image, then setting  $\text{nonlinearity} = 1./\text{noiselevel}$  (or equivalently,  $\text{beta} = \text{noiselevel}$ ) does a decent job at showing the full dynamic range of the image from the peak down to the read noise. Actually I've found that some small multiple of the noiselevel works best, say 5. That makes the asinh scaled image linear in the range of 0 - 5 sigma, then logarithmic for everything brighter.

Oh, this is so slick. I've *got* to start using this for all my plots.

- Marshall

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