Subject: Re: Smoothing 3D array with periodic boundaries: what am I missing? Posted by Luds on Mon, 28 Sep 2009 18:18:05 GMT

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On Sep 28, 4:10 pm, Paolo <pgri...@gmail.com> wrote:
> On Sep 28, 2:56 am, Luds < lud...@uvic.ca> wrote:
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>
>> On Sep 25, 5:52 am, Jeremy Bailin <astroco...@gmail.com> wrote:
>
>>> On Sep 24, 1:19 pm, Luds < lud...@uvic.ca> wrote:
>
>>>> I've been trying for a couple days now to write a Gaussian-smoothing
>>> algorithm to smooth a cube of (scalar) data with periodic boundary
>>> conditions (this is needed for my task since "structure" in the data
>>>> that straddles an edge of the cube appears on two+ sides of the box).
>>>> I've made it so far, but now can't seem to get around excessive For-
>>> loop's...
>>> For example, say the box of scalars values runs from (0,1) in x,y, and
>>> z, and has N<sup>3</sup> points. To smooth at point (x,y,z) in the box I
>>> generate a 3-D Gaussian with its centroid (mean) at point x,y,z:
>>> Gauss_field = rebin(periodic_gauss_func(X,[[sig],[x]]),N,N,N) * $
                    rebin(reform(periodic_gauss_func(X,[[sig],[y]]),
>>>>
>>>> 1,N),N,N,N) * $
                    rebin(reform(periodic_gauss_func(X,[[sig],[z]]),
>>>>
>>>> 1,1,N),N,N,N)
>>> where periodic gauss func is a 1-D Gaussian kernel function that wraps
>>> around the box edge, X=(0,1,...N-1)... sig=sigma. (i.e. this just does
>>> separate Gaussian smoothing along each direction and combines the
>>>> result).
>
>>>> Then the smoothed field at point (x,y,z) is something like
>>> Smoothed(x,y,z) = TOTAL(TOTAL(scalar field*Gauss field,1))
>>> What I can't figure out is an efficient way to do this for all (x,y,z)
>>> - for a N=1024<sup>3</sup> grid it takes a couple seconds to generate
>>> Gauss_field. Realistically, I'll have N=1024^3, so For-loops are
>>> pretty much useless(???), and memory is a bit of an issue too.
>
>>> Does anyone know of any "canned" routines to do this type of Gaussian
>>> smoothing? Or of an efficient way to convolve my 3D Gaussian field
>>> with my scalar field for all (x,y,z)? (I must stress that the Gaussian
>>> kernel must not be affected by, or truncated at, the box edge)
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>>>> Many thanks!!
>>>> Aaron
>>> Wouldn't the Fourier convolution theorem approach work here? FFT your
>>> data cube, FFT your 3D Gaussian kernel, multiply them, and reverse FFT
>>> them back out? You may need to judiciously use TEMPORARY and/or the /
>>> OVERWRITE keyword if memory is an issue.
>
>>> -Jeremy.
>> Yeah, I guess this is the way to go after all.
>
>> I had tried this but didn't really trust my smoothed result. E.g. I
>> attempted to smooth a slab of my data cube with smoothed_field=fft(fft
>> (field)*gaussian filter,1), but only the upper half of the smooth
>> field resembled the original image; the lower half was an inverted
>> backwards copy of the upper half (at least that's what it looked like
>> to my eye). (BTW, it's a Gaussian random field, CDM power-spectrum).
>
>> I guess I'll keep messing around with the IDL's fft. I've read on the
>> help pages that the lowest frequencies in the fft should appear
>> something like a spike in the middle of the fft'd image... I see a
>> spike in the corner (0,0) of the image, which means I probably
>> misinterpreting something simple.
>
 Don't worry - the ordering of the frequencies in FFT nearly
> always is set like that - if that's confusing, a shift of
> half the size of the array will set them the way you expect
 them to be (with 0 frequency in the middle of the array).
>
> To see the effect - take the 1-dim FFT of a gaussian.
> The result is also a gaussian - but you'll need a shift
> of half the size of the array to have it properly centered
  on the middle of the array.
>
> Ciao.
> Paolo
>
>
   Thanks!!
>
>
```

Thank Paolo. Yeah, I figure out the shift of the fft frequencies and now everything is a expected.