# Subject: Re: Map image with a sparse array Posted by Liam E. Gumley on Fri, 21 Jan 2000 08:00:00 GMT

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# whdaffer@my-deja.com wrote:

- I have the following problem. I have an array of geographically
- > colocated data (0.5 by 0.5 degree grid) that is the result of averaging
- > all 253 swaths of one cycle of Topex data into this grid. Topex data has
- > a small (3 or maybe 10km) swath, so the majority of the grid location
- > (65%) are 'bad' in the sense that those grid elements contain no
- > averaged data.

>

- I want to display this by mapping it using map\_set/map\_image. The old >
- > method simply 'tv'd the image to the screen and then finessed applying
- > the continents/grid lines to the image. A bit of a boondogle, and not
- very upgradeable.

>

- The problem is that there seems to be no way to tell map\_image (and >
- > map\_patch too) that certain data (the 'bad' data value) should be
- > excluded from whatever
- > averaging/bilinear-interpolation/nearest-neighbor-chosing method is used
- > and the 'mapped' image has places that are clearly corrupted by the
- > presence of the bad data. The problem is ameliorated by use nearest
- > neighbor rather than bilinear interpolation (i.e. bilinear=0) and I am
- > setting compress=0, so that the inverse transformation is done on each
- > pixel. Also, I've started out with a window set to the size of the input
- > data array and with map set, position=[0.,0,1,1] so that the mapping
- > coordinate system occupies the entire window. These remedies I hit upon
- > thinking that they would minimize the damage, and they have done that,
- > but when I compare my results with the older, more 'pristine' but vastly
- > less portible, upgradeable, maintainable method, there are big
- > differences.

- The 'missing' keyword just sets elements outside the range input via
- > the 'min' and 'max' keywords and those outside of the mapping
- > coordinates to the bad value, it doesn't allow one to exclude data from
- > the averaging/interpolation/chosing method.

## Assuming

- (1) Your data ('grid') is already on a 0.5 x 0.5 degree grid,
- (2) The data range is 0.0 to 100.0 (adjust to taste),
- (3) The missing value is -999.0 (adjust to taste),

image = bytscl(grid, min=0.0, max=100.0, top=!d.table\_size-2) + 1B index = where(grid eq -999.0, count) if (count gt 0) then image[index] = 0B

map\_set, /aitoff, /isotropic
mapped = map\_image(image, startx, starty, xsize, ysize, \$
latmin=-90.0, latmax=90.0, lonmin=-180.0, lonmax=180.0, \$
compress=1, missing=0B, scale=0.05)

loadct, 13, bottom=1 tv, mapped, startx, starty, xsize=xsize, ysize=ysize

Cheers, Liam.

http://cimss.ssec.wisc.edu/~gumley

Subject: Re: Map image with a sparse array Posted by Liam E. Gumley on Mon, 24 Jan 2000 08:00:00 GMT View Forum Message <> Reply to Message

# whdaffer@my-deja.com wrote:

> Can anyone see what I'm doing wrong?

>

- > When I tv the mapped image and compare it to the unmapped image, it's
- > clear that the mapped image has included some 'bad' data in the
- > calculations of points within the grid.

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- > To be fair, this possibility is not explicitly excluded in the help
- > file. If I'm reading it correctly, all it says is that output grid
- > values which are within the valid mapping limits but which exceed input
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- > data' value will be excluded from caluclations.

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- > The effect is not large, but it isn't small either. The person I'm
- > doing the work for noticed it right off.

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- > By the way, I did try your method first, (bytscl, then map image) and
- > got similar results, but thought that I should make the bytscl be the
- > last step, since it reduces the 'color' resolution from 360 values to
- > about 200. I'll go back and try your method again. Perhaps there's some
- > magic that I'm not seeing.

#### William,

I pulled that section of code from a procedure that projects a 720x360 global grid with missing data onto various map projections. I cannot see any hint that the missing data corrupted the resulting image: ftp://origin.ssec.wisc.edu/pub/gumley/IDL/grid\_project002.gi f

#### Cheers.

Liam.

--

Liam E. Gumley

Space Science and Engineering Center, University of Wisconsin-Madison http://cimss.ssec.wisc.edu/~gumley

Subject: Re: Map image with a sparse array Posted by whdaffer on Mon, 24 Jan 2000 08:00:00 GMT View Forum Message <> Reply to Message

In article <3888FAA7.56DC4905@ssec.wisc.edu>,

"Liam E. Gumley" <Liam.Gumley@ssec.wisc.edu> wrote:

> whdaffer@my-deja.com wrote:

>

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- >> colocated data (0.5 by 0.5 degree grid) that is the result of averaging
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   latmin=-90.0, latmax=90.0, lonmin=-180.0, lonmax=180.0, $
   compress=1, missing=0B, scale=0.05)
>
> loadct, 13, bottom=1
> tv, mapped, startx, starty, xsize=xsize, ysize=ysize
> Cheers.
> Liam.
> http://cimss.ssec.wisc.edu/~gumley
>
>
```

This is basically what I'm doing now, except that I'm warping the image to the mapping coordinates first and then byte scaling it.

### Here's my code:

(hlo=-180, hhi=180, which is at about the 3 sigma level of the basic data distribution, baddata=32767, rgb\_missing is the color for the 'bad' data)

```
<quote>
; Monkey with the data.
good = where(gridgood NE baddata,ngood)
bad = where(gridgood EQ baddata, nbad)
gridgood[good] = hlo> gridgood[good] < hhi
```

; Warp the data to the mapped coordinate system
newim = map\_image(gridgood,sx,sy,latmin=minlat,latmax=maxlat,\$
lonmin=0,lonmax=359.5,/compress,\$
min=hlo,max=hhi, missing=baddata)

bad = where(newim EQ baddata,nbad)

; Scale the map from rgb\_lo to rgb\_hi newim = bytscl(newim,min=hlo,max=hhi,top=rgb\_hi-rgb\_lo)+rgb\_lo IF nbad NE 0 THEN newim[bad] = rgb\_missing

</quote>

Can anyone see what I'm doing wrong?

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William

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