Subject: Re: Inverting banded-block matrices.
Posted by Liam E. Gumley on Fri, 29 Aug 2003 15:32:04 GMT
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"James Kuyper" <kuyper@saicmodis.com> wrote in message news:3F4E8B4D.B90EDAA8@saicmodis.com...

- > I've got a problem where I have to calculate g = C D^-1 f, where g and f
- > are vectors, and C and D are matrices. C has m by m blocks, each of
- > which is itself an n by n matrix. It is banded, with k non-zero
- > co-diagonals above and below the main diagnal, both at the block level
- > and within each block. C[i,j] ge 0. Every statement I've made about C
- > also applies to D.
- > For the sake of definiteness, m=10, n=1354, k=3.

>

- > This seems like it should be a pretty common type of matrix structure
- > for problems involving 2-D grids. I could solve this by explicitly
- > inverting a m*n by m*n matrix. However, I would assume that there are
- > existing routines somewhere which can take good advantage of the
- > sparseness of these matrices to speed up the calculations considerably.
- > Could anyone point me at such routines?

I believe LAPACK routines were incorporated in IDL 5.6, however I have not tried them.

Cheers, Liam. Practical IDL Programming http://www.gumley.com/

Subject: Re: Inverting banded-block matrices.

Posted by the_cacc on Sat, 30 Aug 2003 00:30:08 GMT

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James Kuyper kuyper@saicmodis.com wrote in message news:<3F4E8B4D.B90EDAA8@saicmodis.com...

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There are some sparse routines in IDL - sprsin, sprsax, sprsab, sprstp. They're "general" rather than specifically for a certain structure of sparseness, but that should be OK.

Your matrices are pretty big so you can forget about matrix inversion and use an iterative method instead - conjugate gradient (CG) is good.

Actually, can you even store one of those matrices in memory? (I'm on a 80 MB machine so I can't!). If you can, then try

IDL> sparse_D = sprsin(D)

(NB. May be rather slow) If you can't, then you'll have to write a routine to create your matrix in sparse format - hopefully you won't have to do this - trust me :) Let's leave that alone for the moment.

Rewrite as (1)
$$g = C \cdot h$$

(2) $h = D^{-1} \cdot f$

The real work is solving (2). You basically have to solve D \cdot h = f, or sparse_D \cdot h = f, which IDL's linbcg may solve for you.

I found linbcg not so good as the simple CG, which I've implemented. You'd be welcome to use it if you want - but first check if you can create the sparse matrix!

Ciao.