
Subject: Re: Inverting banded-block matrices.

Posted by [Liam E. Gumley](#) on Fri, 29 Aug 2003 15:32:04 GMT

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"James Kuyper" <kuyper@saicmodis.com> wrote in message
news:3F4E8B4D.B90EDAA8@saicmodis.com...

- > I've got a problem where I have to calculate $g = C D^{-1} f$, where g and f
- > are vectors, and C and D are matrices. C has m by m blocks, each of
- > which is itself an n by n matrix. It is banded, with k non-zero
- > co-diagonals above and below the main diagonal, both at the block level
- > and within each block. $C[i,j] \neq 0$. Every statement I've made about C
- > also applies to D .
- > For the sake of definiteness, $m=10$, $n=1354$, $k = 3$.
- >
- > This seems like it should be a pretty common type of matrix structure
- > for problems involving 2-D grids. I could solve this by explicitly
- > inverting a $m*n$ by $m*n$ matrix. However, I would assume that there are
- > existing routines somewhere which can take good advantage of the
- > sparseness of these matrices to speed up the calculations considerably.
- > Could anyone point me at such routines?

I believe LAPACK routines were incorporated in IDL 5.6, however I have not tried them.

Cheers,

Liam.

Practical IDL Programming

<http://www.gumley.com/>

Subject: Re: Inverting banded-block matrices.

Posted by [the_cacc](#) on Sat, 30 Aug 2003 00:30:08 GMT

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news:<3F4E8B4D.B90EDAA8@saicmodis.com>...

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- > sparseness of these matrices to speed up the calculations considerably.
- > Could anyone point me at such routines?

There are some sparse routines in IDL - `sprsin`, `spr sax`, `spr sab`, `sprstp`. They're "general" rather than specifically for a certain structure of sparseness, but that should be OK.

Your matrices are pretty big so you can forget about matrix inversion and use an iterative method instead - conjugate gradient (CG) is good.

Actually, can you even store one of those matrices in memory? (I'm on a 80 MB machine so I can't!). If you can, then try

```
IDL> sparse_D = sprsin(D)
```

(NB. May be rather slow) If you can't, then you'll have to write a routine to create your matrix in sparse format - hopefully you won't have to do this - trust me :) Let's leave that alone for the moment.

Rewrite as (1) $g = C \cdot h$
(2) $h = D^{-1} \cdot f$

The real work is solving (2). You basically have to solve $D \cdot h = f$, or `sparse_D \cdot h = f`, which IDL's `linbcg` may solve for you.

I found `linbcg` not so good as the simple CG, which I've implemented. You'd be welcome to use it if you want - but first check if you can create the sparse matrix!

Ciao.
