Subject: How do I reduce active memory used by program?
Posted by eite2335 on Sun, 19 Mar 2006 20:57:04 GMT
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Dear IDL community,

I wrote a little program which calculates x, y, and z ground control points (gcp) for each pixel
of an image. To do this, I am placing pitch, roll, and yaw parameters into a formula given by
Hongjian and Shukai (2004)

The problem I have is that my program works fine for small images e.g. if I do have only 100 scanlines.
However, if I try to calulate the gcps for larger images (e.g. > than 5000 scanlines) the computer crashes because it uses too much active memory.

I am suspecting that too much active memory is necessary for large images due to the therefore resulting large loops and arrays in my program.

Since I am new to programming I do not really know how to reduce the active memory necessary to run the program for large images.

It would be great if somebody has a suggestion, how to reduce the amount of active memory necessary to run this program so that the program can also be used to calculate gcp's for large images.

I really appreciate your time and help with this

Best regards,

Jan

;; ;;
; Programmer: Jan Eitel
; Last update: 3-17-2006
; Program to calculate x, y, and z ground control points (gcp's) by
using pitch, roll, and yaw variables provided by
; the intertial navigation system.

```
;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;; ;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;;

pro easy_shift

;# of columns in the image

Columns = 752

;# of rows in the image

Rows = 100

;# of loops

rep = (Rows-1)

;; Type in average flying height (fh)

fh = 4000

;; Type in average elevation

elev = 2583

;; Convert flying height and elevation to meters

fh = fh*0.3048

elev = elev*0.3048


;; Calculate flying height above sea level

fhasl = fh - elev


;; Field of view (FOV) per scanline

fov = 15.2483314 * (3.14159265/180)/376


;; Create array. Array will be used to place the calculated internal
geometry values into
```

```
xyz_array = make_array(3, 752, /double, value = 0)

;; calculate the internal geometry of the sensor:

for i = 1, 376 do begin

fovsl = fov * i

x = tan(fovsl)*fhasl

y = x - xyz_array[0, i + 374]

z = fhasl/cos(fovsl)

b = 375 + i

xyz_array[0,b] = x

xyz_array[1,b] = y

xyz_array[2,b] = z

endfor


for i = 1, 376 do begin

b = 376 - i

c = 375 + i

xyz_array[0,b] = xyz_array[0, c] * (-1)

xyz_array[1,b] = xyz_array[1, c] * (-1)

xyz_array[2,b] = xyz_array[2, c]



endfor

;; read in roll, pitch, yaw, xgps, ygps, zgps

openr, 1, 'C:/HC/input1.txt'
```

```
ins = dblarr(5, Rows)

readf, 1, ins


close, 1


;; i is the scanline number (starting with scanline #1)


i = 0

o = ins[0, i]

w = ins[1, i]

k = ins[2, i]

;; populate matrix given in Hongjian and Shukai (2004) and calculate
gcp (ground control points)

a1 = cos(k)*cos(o)

a2 = -cos(k)*sin(o)*sin(w) - sin(k)*cos(w)

a3 = sin(k)*cos(o)

b1 = sin(k)*cos(o)

b2 = -sin(k)*sin(o)*sin(w)+cos(k)*cos(w)

b3 = -sin(k)*sin(o)*cos(w)-cos(k)*sin(w)

c1 = sin(o)

c2 = cos(o)*sin(w)

c3 = cos(o)*cos(w)


matrix1 = make_array(3, 3, /double, value = 0)

matrix1[0,0] = a1

matrix1[1,0] = a2
```

```
matrix1[2,0] = a3

matrix1[0,1] = b1

matrix1[1,1] = b2

matrix1[2,1] = b3

matrix1[0,2] = c1

matrix1[1,2] = c2

matrix1[2,2] = c3



xgps = ins[3, i]

ygps = ins[4, i]

zgps = fhasl

matrix3 = make_array(1, 3, /double, value = 0)

matrix3[0,0] = xgps

matrix3[0,1] = ygps

matrix3[0,2] = zgps


matrix2 = xyz_array




matrix2 = matrix2[0:2,0]

matrix2 = transpose(matrix2)

cf = (matrix1 ## matrix2) + matrix3
```

```
cf_x = cf[0,0]

cf_y = cf[0,1]

cf_z = cf[0,2]


out_x = (cf_x)

out_y = (cf_y)

out_z = (cf_z)



for g = 1, 751 do begin

matrix2 = xyz_array

matrix2 = matrix2[0:2,g]

matrix2 = transpose(matrix2)

cf = (matrix1 ## matrix2) + matrix3

cf_x = cf[0,0]

cf_y = cf[0,1]

cf_z = cf[0,2]


out_x = [[out_x], [cf_x]]

out_y = [[out_y], [cf_y]]

out_z = [[out_z], [cf_z]]
```

```
endfor



for i = 1, rep do begin

o = ins[0, i]

w = ins[1, i]

k = ins[2, i]



;;populate matrix given in Hongjian and Shukai (2004) and calculate gcp
(ground control points)

a1 = cos(k)*cos(o)

a2 = -cos(k)*sin(o)*sin(w) - sin(k)*cos(w)

a3 = sin(k)*cos(o)

b1 = sin(k)*cos(o)

b2 = -sin(k)*sin(o)*sin(w)+cos(k)*cos(w)

b3 = -sin(k)*sin(o)*cos(w)-cos(k)*sin(w)

c1 = sin(o)

c2 = cos(o)*sin(w)

c3 = cos(o)*cos(w)


matrix1 = make_array(3, 3, /double, value = 0)

matrix1[0,0] = a1

matrix1[1,0] = a2
```

```
matrix1[2,0] = a3

matrix1[0,1] = b1

matrix1[1,1] = b2

matrix1[2,1] = b3

matrix1[0,2] = c1

matrix1[1,2] = c2

matrix1[2,2] = c3


xgps = ins[3, i]

ygps = ins[4, i]

zgps = fhasl

matrix3 = make_array(1, 3, /double, value = 0)

matrix3[0,0] = xgps

matrix3[0,1] = ygps

matrix3[0,2] = zgps

matrix2 = xyz_array



matrix2 = matrix2[0:2,0]

matrix2 = transpose(matrix2)

cf = (matrix1 ## matrix2) + matrix3

cf_x = cf[0,0]

cf_y = cf[0,1]

cf_z = cf[0,2]
```

```
out_xx = (cf_x)

out_yy = (cf_y)

out_zz = (cf_z)



for g = 1, 751 do begin

matrix2 = xyz_array

matrix2 = matrix2[0:2,g]

matrix2 = transpose(matrix2)

cf = (matrix1 ## matrix2) + matrix3

cf_x = cf[0,0]

cf_y = cf[0,1]

cf_z = cf[0,2]


out_xx = ([[out_xx], [cf_x]])

out_yy = ([[out_yy], [cf_y]])

out_zz = ([[out_zz], [cf_z]])


endfor

out_x = ([[out_x], [out_xx]])

out_y = ([[out_y], [out_yy]])

out_z = ([[out_z], [out_zz]])
```

```
endfor

;Create arrays to place x, y, z gcp into

output_x = make_array(752, rows, / string, value = 0)

output_y = make_array(752, rows, /string, value = 0)

output_z = make_array(752, rows, /string, value = 0)

counter = lindgen(752, rows)


for i = 0, rep do begin

for j = 0, 751 do begin

counter1 = counter[j, i]

output_x [j, i] = out_x [0, counter1]

output_y [j, i] = out_y [0, counter1]

output_z [j, i] = out_z [0, counter1]

endfor

endfor

;Write x gcp to file

data = output_x

ColumnHeaders=columnHeaders

Filename= 'C:/HC/x_gcp.txt'

width = 10000

;define delimiter

Delimiter = String(9B)
```

```
OpenW, lun, filename, /Get_Lun, Width=width
sData = StrTrim(data,1)
for i = 0, rep do begin
sData[751, i] = sData[751, i]
endfor

PrintF, lun, sData
; Close the file.
Free_Lun, lun


; Write y gcp to file
data1 = output_y
ColumnHeaders=columnHeaders
Filename= 'C:/HC/y_gcp.txt'
width = 10000
Delimiter = String(9B)
OpenW, lun, filename, /Get_Lun, Width=width
sData = StrTrim(data1,1)

for i = 0, rep do begin
sData[751, i] = sData[751, i]
endfor

PrintF, lun, sData
Free_Lun, lun
```

```
;Write y gcp to file

data2 = output_z

ColumnHeaders=columnHeaders

Filename= 'C:/HC/z_gcp.txt'

width = 10000

Delimiter = String(9B)

OpenW, lun, filename, /Get_Lun, Width=width

sData = StrTrim(data2,1)


for i = 0, rep do begin

sData[751, i] = sData[751, i]

endfor


PrintF, lun, sData

Free_Lun, lun


END
```