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Subject: map\_set stereographic projection

Posted by [dvila](#) on Thu, 27 Apr 2006 12:50:50 GMT

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Hi all,

I'm trying to deal with a pre-projected polar stereographic image with this geometrical characteristics:

```
# It is a 1121x881 polar stereographic grid.  
# Point (1,1) is at 23.117N 119.023W.  
# Point (1,881) is at 53.509N 134.039W.  
# Point (1121,1) is at 19.805N 80.750W.  
# Point (1121,881) is at 45.619N 59.959W.  
# The y-axis is parallel to 105W.  
# The resolution is 4.7625km at 60N.  
# The pole point is (I,J) = (400.5,1600.5)
```

I don't know how may I set the map\_set routine to fit the map with the data. Is it possible to work with pre-projected data?

On the other hand, can I change the projection to a regular lat-lon grid in IDL?

Thanks!

Daniel Vila

ESSIC/CICS 2207 Computer & Space Building - Bldg # 224

College Park, MD 20742

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Subject: Re: map\_set stereographic projection

Posted by [James Kuyper](#) on Fri, 28 Apr 2006 17:24:31 GMT

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mattie wrote:

> kuyper@wizard.net writes:

>

>> dvila wrote:

...

>> ; These are the u-v values corresponding to pixel centers along each  
>> edge.

>> topv = (uv[1,1]+uv[1,2])\*0.5

>> botv = (uv[1,0]+uv[1,3])\*0.5

>> leftu = (uv[0,0]+uv[0,1])\*0.5

>> rightu = (uv[0,2]+uv[0,3])\*0.5

>

>

> Aren't these the u-v values corresponding to the \_center\_ of the

> gridcell along each edge? (assuming the initial data gave the

> centerpoints of the gridcell.)

Yes, that's what my comment line says.

```
...
>> ; U-V coordinates of midpoints of outer edges
>> u = [leftu-0.5*xscale, 0.5*(leftu+rightu), rightu+0.5*xscale, $
>>     0.5*(leftu+rightu)]
>> v = [0.5*(botv+topv), topv+0.5*yscale, 0.5*(botv+topv),
>>     botv-0.5*yscale]
>> lonlat = MAP_PROJ_INVERSE(u, v, MAP_STRUCTURE=stereo)
>> limit = [lonlat[1,*],lonlat[0,*]]
>
```

> Again, I'm not sure, but don't you have to add half a gridcell to each  
> direction to get the outter limit of each grid cell?

Yes, that is precisely why I wrote such things as "leftu-0.5\*xscale",  
etc.

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Subject: Re: map\_set stereographic projection  
Posted by [mattie](#) on Fri, 28 Apr 2006 19:41:23 GMT  
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kuyper@wizard.net writes:

```
> mattie wrote:
>> kuyper@wizard.net writes:
>>
>>> dvila wrote:
> ...
>>> ; These are the u-v values corresponding to pixel centers along each
>>> edge.
>>> topv = (uv[1,1]+uv[1,2])*0.5
>>> botv = (uv[1,0]+uv[1,3])*0.5
>>> leftu = (uv[0,0]+uv[0,1])*0.5
>>> rightu = (uv[0,2]+uv[0,3])*0.5
>>
>>
>> Aren't these the u-v values corresponding to the _center_ of the
>> gridcell along each edge? (assuming the initial data gave the
>> centerpoints of the gridcell.)
>
> Yes, that's what my comment line says.
```

Ah, so it does. I read it as the center point of each edge.

```
>>> ; U-V coordinates of midpoints of outer edges
```

```
>>> u = [leftu-0.5*xscale, 0.5*(leftu+rightu), rightu+0.5*xscale, $
>>>    0.5*(leftu+rightu)]
>>> v = [0.5*(botv+topv), topv+0.5*yscale, 0.5*(botv+topv),
>>> botv-0.5*yscale]
>>> lonlat = MAP_PROJ_INVERSE(u, v, MAP_STRUCTURE=stereo)
>>> limit = [lonlat[1,*],lonlat[0,*]]
>>
>> Again, I'm not sure, but don't you have to add half a gridcell to each
>> direction to get the outter limit of each grid cell?
>
> Yes, that is precisely why I wrote such things as "leftu-0.5*xscale",
```

Yup again. When I looked at it, I kept thinking u was upper, rather than the uv direction, and it's completely obvious now. I was getting thrown by the u[1] factor as (leftu + rightu) \* .5.

So I don't have any reason to say "But" when I said:

"But this was a very informative tutorial on how to register images when corner points are known."

Thanks for the lesson.

Matt

--

Matthew Savoie - Scientific Programmer  
National Snow and Ice Data Center  
(303) 735-0785 <http://nsidc.org>

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Subject: Re: map\_set stereographic projection  
Posted by [David Fanning](#) on Fri, 28 Apr 2006 19:52:21 GMT  
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Mr. Kuyper,

What can you tell us about UV coordinates? The IDL documentation is (as usual) silent about this point, simply referring to them as "XY Cartesian coordinates". Do we know, or care, what they *really* are?

An hour search on Goggle was equally unenlightening, except in referring to UV coordinates in the context

of texture mapping, which I assume is not \*really\*  
how they are being used here.

And please, sir, tell us how you stumbled onto using  
MAP\_PROJ\_\* functions to solve this registration problem.

Cheers,

David

--

David Fanning, Ph.D.

Fanning Software Consulting, Inc.

Coyote's Guide to IDL Programming: <http://www.dfanning.com/>

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Subject: Re: map\_set stereographic projection

Posted by [James Kuyper](#) on Fri, 28 Apr 2006 22:59:20 GMT

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David Fanning wrote:

- > Mr. Kuyper,
- >
- > What can you tell us about UV coordinates? The IDL
- > documentation is (as usual) silent about this point,
- > simply referring to them as "XY Cartesian coordinates".
- > Do we know, or care, what they \*really\* are?

Every map "projection", whether or not it's geometrically describable as a projection, maps lat-lon positions on the surface of the earth to a positions on a flat plane in space. It's conventional to use u and v as the names of an orthogonal coordinate system describing positions on that flat plane. A second, trivial scale-and offset mapping usually connects positions on this plane to positions on your actual printed map. U/V coordinates are used for the flat plane, because x and y are reserved for the position on the printed map. In IDL terms, x and y are device coordinates.

The relationship between lat/lon and u/v depends upon the map projection. If you're familiar with the geometric definition of the particular map projection you're working with, the relationship is usually unsurprising. If you're not familiar with the map projection, I suppose the relationship would probably be very difficult to figure out, but I wouldn't know about that :-). What I generally do is use MAP\_PROJ to calculate a few key positions, so I can figure out what choices they've made. For polar projections they generally use a plane tangent to the earth at the center of the projection, with a scale in meters and the u-v coordinates oriented toward local East and local

North respectively, at the point of tangency. For cylindrical projections, they use a plane wrapped around the earth at the equator, with it's center at the center point of the projection, with a scale in meters, and U/V oriented toward local East/North at the center point.

However, I generally try to avoid building assumptions about the scaling and orientation of the axes into my code. The V direction, in particular, sometimes points north and sometimes south. There's a couple of projections where they appear to use a plane tangent to a unit sphere, rather than one tangent to the surface of the Earth, which means that the scaling is equivalent to radians instead of meters near the center of the projection. What I do to cope with these issues is convert a few well-chosen positions to U/V coordinates, and use the values for those positions to resolve any such ambiguities.

- > An hour search on Goggle was equally unenlightening,
- > except in referring to UV coordinates in the context
- > of texture mapping, which I assume is not *\*really\**
- > how they are being used here.
- >
- > And please, sir, tell us how you stumbled onto using
- > MAP\_PROJ\_\* functions to solve this registration problem.

I've always been fascinated by map projections. I had a very clear understanding of them before I ever ran into the IDL map projection routines. My current job has required me to become familiar with the GCTP map projection library. Before the MAP\_PROJ\_\* routines came out, I used MAP\_SET and COORD\_CONV for similar purposes, but I immediately recognised the MAP\_PROJ\_\* as an easier way to do things.

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Subject: Re: map\_set stereographic projection  
Posted by [David Fanning](#) on Fri, 28 Apr 2006 23:06:20 GMT  
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Folks,

I've written a short article on this topic, which you can find here:

[http://www.dfanning.com/map\\_tips/precipmap.html](http://www.dfanning.com/map_tips/precipmap.html)

I'm especially interested in debugging this code, so read it quickly. :-)

In addition to the interesting topic of fitting a map projection to an image (which I'm sure you know is just the *\*opposite\** of the way IDL normally does things), I

show you how to use my COLORBAR routine to display a non-linear color scheme. (I knew it could do it, I just didn't know how!)

Flail away!

Cheers,

David

--

David Fanning, Ph.D.

Fanning Software Consulting, Inc.

Coyote's Guide to IDL Programming: <http://www.dfanning.com/>

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Subject: Re: map\_set stereographic projection  
Posted by [James Kuyper](#) on Sat, 29 Apr 2006 04:18:37 GMT  
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David Fanning wrote:

> Folks,  
>  
> I've written a short article on this topic, which you can  
> find here:  
>  
> [http://www.dfanning.com/map\\_tips/precipmap.html](http://www.dfanning.com/map_tips/precipmap.html)

Thanks for the citation - I'm glad I could help! You explained what I was doing more clearly than I could have, even if I'd had the time to do so.

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Subject: Re: map\_set stereographic projection  
Posted by [dvila](#) on Mon, 01 May 2006 15:12:14 GMT  
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I agree with Kuyper, the article is very clear. Thank for the citation and I hope that this example can be usefull for many others IDL users. Thanks again, David

Daniel

kuyper@wizard.net wrote:

> David Fanning wrote:  
>> Folks,  
>>  
>> I've written a short article on this topic, which you can

>> find here:  
>>  
>> [http://www.dfanning.com/map\\_tips/precipmap.html](http://www.dfanning.com/map_tips/precipmap.html)  
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> Thanks for the citation - I'm glad I could help! You explained what I  
> was doing more clearly than I could have, even if I'd had the time to  
> do so.

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