
Subject: Re: Point Cloud Isosurface

Posted by [Karl\[1\]](#) on Thu, 12 Aug 2010 21:27:02 GMT

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On Aug 12, 2:42 pm, tegus <tegusbillhar...@gmail.com> wrote:

> Hello,
> I'm working with noisy 3D point cloud data approximated by:
> xyz_0=randomn(seed, 3, 1000) + 5.0
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> objects (verts1, conn1 and verts2, conn2)?
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> Thanks,
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MESH_CLIP() ?

Subject: Re: Point Cloud Isosurface

Posted by [tegus](#) on Fri, 13 Aug 2010 01:55:31 GMT

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On Aug 12, 5:27 pm, Karl <karl.w.schu...@gmail.com> wrote:

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Subject: Re: Point Cloud Isosurface
 Posted by [Karl\[1\]](#) on Fri, 13 Aug 2010 14:58:11 GMT
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These lists refer to the original vertex list. You can leave it that way and just reference the original vertex list from the grPolygon objects. So you would use verts (the original vert list) and blob_conn1 in a grPolygon object to represent the first blob.

If putting the entire vertex list in each polygon object is bad, as I suspect it is, you can do additional work to pull the vertices referenced by each conn list out of the original vert list and make a new, smaller, vert list for each blob. Then you can delete the original vertex list.

This will likely be a good path since there are likely no shared verts between blobs.

You'll have to be careful when pulling the verts out since you'll have to remap the conn indices and pay attention to verts used more than once, etc. But it can all be done pretty easily.

And all this assumes that each blob is represented by one polygon in the original polygon object. If that is not the case, you'll have to do some more work to find all the polys that belong to a blob.

Subject: Re: Point Cloud Isosurface

Posted by [tegus](#) on Fri, 13 Aug 2010 17:15:31 GMT

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On Aug 13, 10:58 am, Karl <karl.w.schu...@gmail.com> wrote:

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Karl,

Thank you for your insight. This helps a great deal!!

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Actually, I don't think it will help much. I just recalled that
ISOSURFACE probably emits independent triangles. So all the "n"s
will be 3, and that isn't good to do what you want.

Here is one really slow approach:

All the triangles in a blob should be vertex-connected to other tris
in the blob. So, you could pick and remove the first triangle from
the list. Then find another triangle in the original list that shares
a vert with any triangle in your current blob tri list. Remove this
tri from the main list and add it to the blob list. Repeat until no
more tris in the main list match any vert in the blob list. Then
start a new blob by taking the first tri in the remaining main list
and start the process again, repeating until the main list is empty.

The polygon returned by ISOSURFACE does not repeat verts in the vertex
list, so you can just compare connectivity indices when comparing
verts.

There may be some clever ways to implement this in IDL to make it run
fast enough, but there will probably be a lot of looping which will be
pretty slow if there are a lot of triangles.
