Subject: Re: IDL fitting of piecewise continuous function Posted by Jeremy Bailin on Tue, 17 May 2011 19:21:49 GMT

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Craigh Markwardt's MPFIT (and its varients) is most people's preferred fitting routine:

http://www.physics.wisc.edu/~craigm/idl/fitting.html

You define your own function to feed in, so it can have whatever behaviour you want. To ensure continuity, I would recommend re-parametrizing the functional form so that it is continuous by definition. In this, case, A and B aren't actually independent, so calculate B in terms of A by setting them equal at $x=x_m$, which gives $B = A x_m^3$

So you're actually fitting:

$$f(x) = A x_m^{(1/2)} x^{(1/2)} x < x_m$$

 $A x_m^{(3/2)} x^{(-1)} x > x_m$

-Jeremy.

Subject: Re: IDL fitting of piecewise continuous function Posted by Jeremy Bailin on Tue, 17 May 2011 19:24:25 GMT View Forum Message <> Reply to Message

sorry, that should be:

$$f(x) = A x^{(1/2)} x < x_m$$

 $A x m^{(3/2)} x^{(-1)} x > x m$

-Jeremy.

Subject: Re: IDL fitting of piecewise continuous function Posted by Sasha Singh on Tue, 17 May 2011 19:26:41 GMT View Forum Message <> Reply to Message

Thanks Jeremy,

I did look look at MPFIT. I am confused as to how do I define the constraints $x < x_m$ and $x > x_m$ in the function. Sorry I am quite new to IDL.

Sasha

On May 17, 3:21 pm, Jeremy Bailin <astroco...@gmail.com> wrote:

> Craigh Markwardt's MPFIT (and its varients) is most people's preferred fitting routine:

> http://www.physics.wisc.edu/~craigm/idl/fitting.html

> You define your own function to feed in, so it can have whatever behaviour you want. To ensure continuity, I would recommend re-parametrizing the functional form so that it is continuous by definition. In this, case, A and B aren't actually independent, so calculate B in terms of A by setting them equal at x=x_m, which gives

> B = A x_m^(3/2)

> So you're actually fitting:

> f(x) = A x_m^(1/2) x^(1/2) x < x_m

> A x_m^(3/2) x^(-1) x > x_m

> -Jeremy.

Subject: Re: IDL fitting of piecewise continuous function Posted by Jeremy Bailin on Tue, 17 May 2011 19:53:19 GMT

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If you define your function analogously to the example in the MPFIT code, it might look like:

```
FUNCTION MYFUNCT, p, X=x, Y=y, ERR=err
; p[0] is A
x_m = SOME_CONSTANT_VALUE

; x It x_m is 1 if x<x_m and 0 otherwise
; x ge x_m is 1 if x >= x_m and 0 otherwise
model = (x It x_m) * p[0] * x^(0.5) + (x ge x_m) * p[0] * x_m^(1.5) / x

return, (y-model)/err
END
```

Of course, that assumes that x_m is a constant, not a parameter - but if it's a parameter, you would just use p[1] instead of a constant value, for example.

-Jeremy.

Subject: Re: IDL fitting of piecewise continuous function Posted by Craig Markwardt on Wed, 18 May 2011 02:35:13 GMT View Forum Message <> Reply to Message

```
On May 17, 3:53 pm, Jeremy Bailin <astroco...@gmail.com> wrote:
> If you define your function analogously to the example in the MPFIT code, it might look like:
> FUNCTION MYFUNCT, p, X=x, Y=y, ERR=err
   ; p[0] is A
>
>
   x_m = SOME_CONSTANT_VALUE
>
   ; x lt x_m is 1 if x<x_m and 0 otherwise
>
   ; x ge x_m is 1 if x \ge x_m and 0 otherwise
   model = (x lt x_m) * p[0] * x^{0.5} + (x ge x_m) * p[0] * x_m^{1.5} / x
>
>
   return, (y-model)/err
> END
>
> Of course, that assumes that x_m is a constant, not a parameter - but if it's a parameter, you
would just use p[1] instead of a constant value, for example.
```

Yep, what he said. Craig

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