
Subject: Object Tree

Posted by [J.D. Smith](#) on Mon, 16 Nov 1998 08:00:00 GMT

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I've made an Object-Based tree that might be useful... Basically, to use it, derive a class from it, complete with node data, and possible data collection, and/or modification methods. Each instance of this class is a single node in a Tree, and contains two pointers: children and siblings, specifying a list of this node's children (may have none), and siblings (at least one... itself).

Things you can do with it:

- *Add children and/or siblings to a given node.
- *Delete a given node and all descendents.
- *Delete an entire tree *except* a given node and descendents, replacing the Tree.
- *Obtain a list of a node's descendents.
- *Obtain a list of all leafs (childless nodes) beneath a node.
- *Visit all descendents or all descending leafs and call a specified method on them (for data collection or modification). This is where the real work is done.

All recursion is depth-first.

As an example of what can be done, I made a toy "TicTacToe" class which populates the entire game tree for this simple game. I visit all endgames (leafs), and collect win/loss statistics. This tree had around 350,000 nodes.

If you have data which is naturally organized heirarchically, this may be useful for you.

JD

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J.D. Smith |*| WORK: (607) 255-5842
Cornell University Dept. of Astronomy |*| (607) 255-6263
304 Space Sciences Bldg. |*| FAX: (607) 255-5875
Ithaca, NY 14853 |*|

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;+  
; NAME: ObjTree  
;  
; PURPOSE: A Object Based data Tree  
;  
; CATEGORY: Object-Based Data Manipulation  
;  
; METHODS:
```

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;
; CHILDREN(): Return this node's child object(s).
;
;
; SIBLING(): Return this node's sibling object(s)
;
;
; SETVALUE: Sets Object Data Values -- use ADD unless custom addition.
; KEYWORDS: Each keyword sets the corresponding member data with the
; passed value, which can either be an object list or pointer to one.
; CHILDREN: The node's children
; SIBLINGS: The node's siblings ... points also to parent's
; children list.
;
;
; LEAFS, list: return a list of all leafs below this node.
;
;
; FAMILY, list: return a list of all of this node's descendents.
;
;
; VISIT, method: Recursively call method method on all descendents,
; passing it any extra keywords (which might be required to effect
; any modification of the node data).
;
;
; LEAFVISIT, method: Same as visit, but only for leafs.
;
;
; ADD, entry: Add the object entry to this node.
; KEYWORDS:
; SIBLING: Add entry as a sibling instead of default child.
; NOTE: An added sibling is always younger than any existing siblings.
; An added child inherits is made the sibling of any existing children.
;
;
; DELETE: Delete this node, and all of its descendents (recursively).
; NOTE: If this node has a parent, its child reference is assigned
; to the next younger sibling, if no older siblings exist. If no other
; siblings exist at all, the parent's child reference is cleared.
;
;
; PRUNE: Delete the entire tree *except* this node and its descendents,
; leaving this node as the root of the Tree.
;
;
; CLEANUP: (Automotically called)
;
;
; NOTES: Each node in the tree is represented by a single instance
; of this class. This tree has these properties: A node's list of
; children is the same list as its children's list of siblings.. not
; a copy, the *same* list -- modifying the children list at the same
; time modifies the children's sibling list. New generations can
; only be added at extremities of the tree, i.e. at those nodes
; which don't yet have children. Otherwise, new children will join
; those children already living. You may use SetValue to circumvent
; these limits, but beware: inbred trees may result.
;
;

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;
; MODIFICATION HISTORY:
; 11/13/98 -- Added Leafs and LeafVisit. JDS
;   6/4/98 -- Removed Gen, changed ModPro to a Call_Method in Method. JDS
;   5/12/98 -- JD Smith
;-

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```

function ObjTree::Children
    return, self.children
end

```

```

function ObjTree::Siblings
    return, self.siblings
end

```

```

pro ObjTree::SetValue, CHILDREN=child, SIBLINGS=sib
    if keyword_set(child) then begin
        ;; find out if list or pointer is passed
        s=size(child,/TYPE)
        if s eq 10 then begin ;it's a pointer
            if child ne self.children then begin ;points at different heap vars?
                ptr_free, self.children ;free memory of old list
                self.children=child
            endif
        endif else begin
            if ptr_valid(self.children) then *self.children=child $
            else self.children=ptr_new(child)
        endelse
    endif
    if keyword_set(sib) then begin
        s=size(sib,/TYPE)
        if s eq 10 then begin ;it's a pointer
            if sib ne self.siblings then begin ;point at different heap vars?
                ptr_free, self.siblings
                self.siblings=sib
            endif
        endif else begin
            *self.siblings=sib ;siblings must be valid, since *we're* alive.
        endelse
    endif
end

```

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;=====
;=====
; Leafs - Find all of the Leaves below me
;=====
;=====
pro ObjTree::Leafs,list

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c=self.children
if ptr_valid(c) then begin
  for i=0,n_elements(*c)-1 do (*c)[i]->Leafs, list
endif else begin ; I am a leaf!
  if n_elements(list) eq 0 then list=self else list=[list,self]
endelse
end

```

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;=====
;
; Family - Recurs over my decedents and return a list of them.
;=====

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pro ObjTree::Family,list
  c=self.children
  if ptr_valid(c) then begin
    if n_elements(list) eq 0 then list=[*c] else list=[list,*c]
    for i=0,n_elements(*c)-1 do (*c)[i]->Family, list
  endif
end

```

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;=====
;
; Visit: Recurs over my descendents, modifying the node data with a
; method "Method" (presumably of an inheriting class). Any keywords
; passed are given directly to Method to do with as it pleases
; (though in general it will modify or collect data). As a simple
; example, suppose each node had some data member which needed to be
; incremented. A method 'Increment' could do this, and be passed the
; INCREMENT to perform (as a keyword).
; e.g. thisNode->Visit, 'Increment',INCREMENT=10
; Or maybe you need to collect some data, with
; e.g. thisNode->Visit, 'DataCollect', OUTDATA=out
; for putting a summary of data into "out" (_REF_EXTRA is employed).
;=====

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pro ObjTree::Visit,Method,_REF_EXTRA=e
  if ptr_valid(self.children) then $
    for i=0, n_elements(*self.children)-1 do begin
      Call_Method,Method,(*self.children)[i],_EXTRA=e
      (*self.children)[i]->Visit,Method, _EXTRA=e ;recurs, depth first!
    endfor
end

```

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;=====
;
; LeafVisit: Same as Visit except on underlying leafs only.
;=====

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=====
pro ObjTree::LeafVisit, Method, _REF_EXTRA=e
  if ptr_valid(self.children) then begin
    for i=0, n_elements(*self.children)-1 do $
      (*self.children)[i]->LeafVisit,Method, _EXTRA=e
    endif else begin
      Call_Method, Method, self, _EXTRA=e
    endelse
  end
end

```

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; Add: Add element(s), as either children or siblings (children
; by default), to the current node (this object instance).
; Siblings added are always younger (later in list) than any existing
; siblings.. and children added are assigned to be younger than
; any children already present, and at their depth. This means
; that new generations can only be created at the bottom of the
; tree (if the root is at the top).
;=====

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=====
pro ObjTree::Add, list, SIBLINGS=sib
  if keyword_set(sib) then begin ;inserting new sibling(s)
    ;; add them to the end of my list
    *self.siblings=[*self.siblings,list]
    ;; set their siblings array the same as mine, freeing any old siblings
    ;; list if any (shouldn't have any, inbred trees are trouble!)
    for i=0,n_elements(list)-1 do $
      list[i]->SetValue,SIBLINGS=self.siblings
    endif else begin ;inserting a new child
      if ptr_valid(self.children) then begin
        ;; add the children at the end of my children list
        *self.children=[*self.children,list]
      endif else begin
        self.children=ptr_new(list)
      endelse
      ;; set their *siblings* array be my *children* array, freeing any
      ;; siblings list if any (but there shouldn't really be).
      for i=0,n_elements(list)-1 do $
        list[i]->SetValue,SIBLINGS=self.children
      endelse
    end
  end
end

```

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;=====
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; Delete: Delete this node and all descendents, clearing
; the child list of its parent if this node has no siblings.
;=====

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=====
pro ObjTree::Delete
  sibs=n_elements(*self.siblings) ;if only 1, I'm an only child.
  if sibs eq 1 then self.siblings=ptr_new() else $
    *self.siblings=(*self.siblings)[where(*self.siblings ne self)]
  obj_destroy,self          ;call cleanup recursively to kill descendents
end

;=====
=====
; Prune: Delete everything in Tree except this node and it's
; descendents, leaving this node as the root of the Tree.
;=====
=====
pro ObjTree::Prune, Tree
  ;; remove myself from my list of siblings (and from my parents list of
  ;; children -- it's the same list!!)
  if n_elements(*self.siblings) gt 1 then $
    *self.siblings=(*self.siblings)[where(*self.siblings ne self)] $
  else $
    self.siblings=ptr_new()    ;I was an only child

  ;; Destroy the tree around us, as we hide, not on the list for destruction.
  obj_destroy,Tree
  Tree=self          ;I am now the root of this tree!
end

;=====
=====
; Cleanup: Recursively destroy all descendents, depth first.
;=====
=====
pro ObjTree::Cleanup
  ;; Call Cleanup on children first, then cleanup the siblings list (which
  ;; will also free the children list of the siblings' parent).
  if ptr_valid(self.children) then begin
    obj_destroy,*self.children
  endif
  if ptr_valid(self.siblings) then ptr_free,self.siblings
end

;=====
=====
; ObjTree__define: define the ObjWidget Class structure
;=====
=====
pro ObjTree__define
  ;; define a tree member class

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```
struct={ObjTree, $
    siblings:ptr_new(),$ ;an array of siblings (at least including me!)
    children:ptr_new()} ;an array of children (possibly childless)
end
```

File Attachments

1) [objtree__define.pro](#), downloaded 124 times
